

GasTurb



Turbojet Deck

Joachim Kurzke

Turbojet Deck

Steady State Performance

by Joachim Kurzke

Turbojet Deck

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1 GasTurb Computer Deck

The GasTurb Turbojet Deck is a computer deck as defined in the SAE Aerospace Standard AS681. The actual engine subroutine is contained in a [Dynamic Link Library \(DLL\)](#). The use of the engine subroutine is demonstrated both with a Delphi test main program and with an Excel macro. The Dynamic Link Library can be used with any other 32-bit Windows program.

The data describing the engine are created with GasTurb 12 as an Engine Model File which is loaded during the Turbojet Deck initialization process. The Engine Model File contains all data necessary for doing off-design simulations, both for steady state and transient operation. Maximum and minimum limiters as well as bleed schedules must be defined in the engine model. It is strongly recommended to check this model thoroughly with GasTurb 12 before using it with the Turbojet Deck DLL.

Transient simulations can employ the control system as defined in the GasTurb 12 model or run to a specified fuel flow or spool speed.

2 Engine Description

With this generic computer deck the performance of [single spool turbojet engines without afterburner](#) can be calculated. Which engine is modeled in particular depends on the Engine Model File created with GasTurb 12.

3 Program Description

The Turbojet Deck has been developed with Delphi XE4 running under Windows 8. The test main program has a standard windows user interface and calls functions from the Turbojet Deck DLL which contains the actual engine simulation model. An alternative use of the Turbojet Deck is shown as an Excel application in the file TurbojetDeckDemo.xls

4 Program Setup

4.1 General

The Turbojet Deck calls functions from a DLL which can be used with any Windows program. In the test main program this DLL is employed by a Delphi program, in the file TurbojetDeckDemo.xls the functions of the DLL are called from an Excel macro. Before commencing with the engine simulation the functions in the DLL must be initialized. During initialization an Engine Model File created with GasTurb 12 is read from file and evaluated. The required organization of the files is as summarized in the table below. Note that the Data Directory can be the same as the DLL Directory.

| DLL Directory | Data Directory |
|-------------------------------|--|
| TurbojetDeckLib.DLL | An Engine Model File, created with GasTurb 12 |
| LoadOptions.NMS | Component map data files referenced in the Engine Model File |
| Turbojet.NMS | Fuels.gtb and all files referenced in Fuels.gtb |

4.2 DLL Interface

The DLL contains the functions and procedures (subroutines) listed in the table. Note that when declaring the functions and subroutines in a VBA program within Excel, for example, the expression [{Path to the DLL}](#) in the table below must be replaced by the actual path to the DLL on the users machine.

| Delphi | Visual Basic for Applications (VBA) |
|--|--|
| function GetDLLVersion : double; | Declare Function GetDLLVersion Lib "{Path to the DLL}\TurbojetDeckLib.dll" () As Double |
| procedure WriteFIXIN (ZCASEFI,ZALTFI,ZDTAMBFI,ZERM1AFI,ZPWXHF, HFI, ZPAMBFI,ZPCFI, ZPLAFI,ZP1AFI,ZRCFI,SERAMFI, SIMFI,ZTAMBFI,ZT1AFI,ZWB3FI,ZWB3QFI,ZXMF, FI, ZTIMEFI : double); | Declare Sub WriteFIXIN Lib "{Path to the DLL}\TurbojetDeckLib.dll" (ByVal ZCASEFI#, ByVal ZALTFI#, ByVal ZDTAMBFI#, ByVal ZERM1AFI#, ByVal ZPWXHF#, ByVal ZPAMBFI#, ByVal ZPCFI#, ByVal ZPLAFI#, ByVal ZP1AFI#, ByVal ZRCFI#, ByVal SERAMFI#, ByVal SIMFI#, ByVal ZTAMBFI#, ByVal ZT1AFI#, ByVal ZWB3FI#, ByVal ZWB3QFI#, ByVal ZXMF#, ByVal ZTIMEFI#) |
| procedure ReadFIXIN (var ZCASEFI,ZALTFI,ZDTAMBFI,ZERM1AFI, ZPWXHF,ZPAMBFI,ZPCFI,ZPLAFI,ZP1AFI,ZRC FI, SERAMFI,SIMFI,ZTAMBFI,ZT1AFI,ZWB3FI,ZW B3QFI, ZXMF,ZTIMEFI : double); | Declare Sub ReadFIXIN Lib "{Path to the DLL}\TurbojetDeckLib.dll" (ZCASEFI#, ZALTFI#, ZDTAMBFI#, ZERM1AFI#, ZPWXHF#, ZPAMBFI#, ZPCFI#, ZPLAFI#, ZP1AFI#, ZRCFI#, SERAMFI#, SIMFI#, ZTAMBFI#, ZT1AFI#, ZWB3FI#, ZWB3QFI#, ZXMF#, ZTIMEFI#) |
| procedure WriteVARIN (ZHUMIDVI,ZFHVVI,ZFNVI,ZWFVI,ZXNRPMVI, ZWRCQ2VI,SESTVI,ZBTACVI,ZRXNHVI,ZT4VI, ZBTATVI,ZDTRCVI,STRANSVI,ZCTRCPVI,ZCTR CDVI, ZCTRCIVI : double); | Declare Sub WriteVARIN Lib "{Path to the DLL}\TurbojetDeckLib.dll" (ByVal ZHUMIDVI#, ByVal ZFHVVI#, ByVal ZFNVI#, ByVal ZWFVI#, ByVal ZXNRPMVI#, ByVal ZWRCQ2VI#, ByVal SESTVI#, ByVal ZBTACVI#, ByVal ZRXNHVI#, ByVal ZT4VI#, ByVal ZBTATVI#, ByVal ZDTRCVI#, ByVal STRANSVI#, ByVal ZCTRCPVI#, ByVal ZCTRCDVI#, ByVal ZCTRCIVI#) |

| | |
|--|--|
| <pre> procedure ReadVARIN (var ZHUMIDVI,ZFHVVI,ZFNVI,ZWFVI,ZXNRPMVI, ZWRCQ2VI,SESTVI,ZBTACVI,ZRXNHVI,ZT4VI,Z BTATVI, ZDTRCVI,STRANSVI,ZCTRCPIVI,ZCTRCDVI,ZCT RCIVI : double); </pre> | <pre> Declare Sub ReadVARIN Lib "{Path to the DLL}\TurbojetDeckLib.dll" (ZHUMIDVI#, ZFHVVI#, ZFNVI#, ZWFVI#, ZXNRPMVI#, ZWRCQ2VI#, SESTVI#, ZBTACVI#, ZRXNHVI#, ZT4VI#, ZBTATVI#, ZDTRCVI#, STRANSVI#, ZCTRCPIVI#, ZCTRCDVI#, ZCTRCIVI#) </pre> |
| <pre> procedure ReadFIXOUT (var NSIFO,AE8FO,FRAMFO,FGFO,FHVFO,FNFO, PB3FO,P7FO,SFCFO,TB3FO,T7FO,WFEFO,W FTFO, W1AFO,W7FO,W2FO,XNHFO,ALTFO,PAMBF O,PLAFO, P1AFO,TAMBFO,T1AFO,XMFO,SMHFO,TIMEF O, ERAM1FO,DTAMBFO,PCFO,RCFO,WB3FO,W B3QFO, PWXHFO : Double); </pre> | <pre> Declare Sub ReadFIXOUT Lib "{Path to the DLL}\TurbojetDeckLib.dll" (NSIFO#, AE8FO#, FRAMFO#, FGFO#, FHVFO#, FNFO#, PB3FO#, P7FO#, SFCFO#, TB3FO#, T7FO#, WFEFO#, WFTFO#, W1AFO#, W7FO#, W2FO#, XNHFO#, ALTFO#, PAMBFO#, PLAFO#, P1AFO#, TAMBFO#, T1AFO#, XMFO#, SMHFO#, TIMEFO#, ERAM1FO#, DTAMBFO#, PCFO#, RCFO#, WB3FO#, WB3QFO#, PWXHFO#) </pre> |
| <pre> procedure ReadVAROUT (var humidVO, T2VO, T3VO, T4VO, T41VO, T5VO, P3VO, Ps3VO, P5VO, NHDOT, FAR4, LIMCD, BTA CVO, RXNHVO, BTATVO, DTRCVO : Double); </pre> | <pre> Declare Sub ReadVAROUT Lib "{Path to the DLL}\TurbojetDeckLib.dll" (humidVO#, T2VO#, T3VO#, T4VO#, T41VO#, T5VO#, P3VO#, Ps3VO#, P5VO#, NHDOT#, FAR4#, LIMCD#, BTACVO#, RXNHVO#, BTATVO#, DTRCVO#) </pre> |
| <pre> procedure InitializeEngine (DLLPath,FileName : PChar); </pre> | <pre> Declare Sub InitializeEngine Lib "{Path to the DLL}\TurbojetDeckLib.dll" (ByVal DLLPath\$, ByVal Filename\$) </pre> |
| <pre> procedure SinglePoint; </pre> | <pre> Declare Sub SinglePoint Lib "{Path to the DLL}\TurbojetDeckLib.dll" () </pre> |

4.3 DLL Function Call Sequence

DLL Initialization

During initialization of the DLL the files in the DLL directory and in the Engine Model File directory are read. Furthermore, the cycle reference point is calculated which yields all the output quantities for this operating condition. After the call of [InitializeEngine](#) all the elements of FIXIN, VARIN, FIXOUT and VAROUT can be read by the DLL calling program:

InitializeEngine

ReadFIXIN

ReadVARIN

ReadFIXOUT

ReadVAROUT

If after the initialization the VARIN property **SEST** is set to 1, then the following single point calculation will employ as starting values of the iteration the properties ZBTAC, ZRXNH, ZT4, ZBTAT and ZDTRC. It is a good idea to write the results (i.e. the VAROUT properties BTAC, RXNH, BTAT and DTRC) to the corresponding input properties immediately after calling **InitializeEngine**. Thus there are reasonable estimates for the iteration variables readily available for the use with **SEST=1** if convergence problems are encountered.

Using the DLL for steady state simulations

The procedure (subroutine) **SinglePoint** calculates a single cycle point either in steady state (ZTIME=0) or transient mode (ZTIME>0). Before calling the actual simulation function **SinglePoint** the input data stored in the FIXIN and VARIN properties must be transferred to the DLL by calling the procedures **WriteFIXIN** and **WriteVARIN**. After the cycle calculation is finished, the results can be read from the DLL by calling the procedures **ReadFIXOUT** and **ReadVAROUT**:

WriteFIXIN

WriteVARIN

SinglePoint

ReadFIXOUT

ReadVAROUT humid, T2, T3, T4, T41, T5, P3, Ps3, P5, NHDOT, FAR4, LIMCD, BTAC, RXNH, BTAT, DTRC

Using the DLL for transient simulations

The procedure (subroutine) **SinglePoint** calculates a single point in transient mode for the time = ZTIME (defined in FIXIN) which must be greater than the value TIME (defined in VAROUT) of the previously calculated point. The begin of the transient maneuver is the operating condition that was calculated with ZTIME=0 immediately before ZTIME is set to a value greater than zero.

ZTIME=0

repeat

WriteFIXIN

WriteVARIN

SinglePoint

ReadFIXOUT

ReadVAROUT

ZTIME=TIME+delta time

until ZTIME > end time

4.4 Test Main

The Test Main program has been created and compiled with Delphi XE4. It provides a graphical user interface for the functions and procedures in the DLL.

Before commencing with simulations, the DLL must be initialized by loading an Engine Model File which was created with GasTurb 12. Note that the component maps employed in the Engine Model File must be stored in the same directory as the Engine Model File as described on the general introduction to the program setup.

On the steady state input page the input properties for a single point are offered. The input properties are grouped as FIXIN and VARIN, the output properties are shown in the groups FIXOUT and VAROUT.

The transient page of the test main program offers the following three simulation examples:

- A step increase of 10% in fuel flow (GasTurb 12 control system inactive)
- A PLA maneuver with activated control system as described with the Engine Model File
- An example with prescribed spool speed (GasTurb 12 control system inactive)

Each transient maneuver commences with the steady state condition calculated before switching to transient simulations.

4.5 Excel Application

The file TurbojetDeckDemo.xls - which is delivered as part of the software package - demonstrates the use of the Turbojet Deck DLL with Excel.

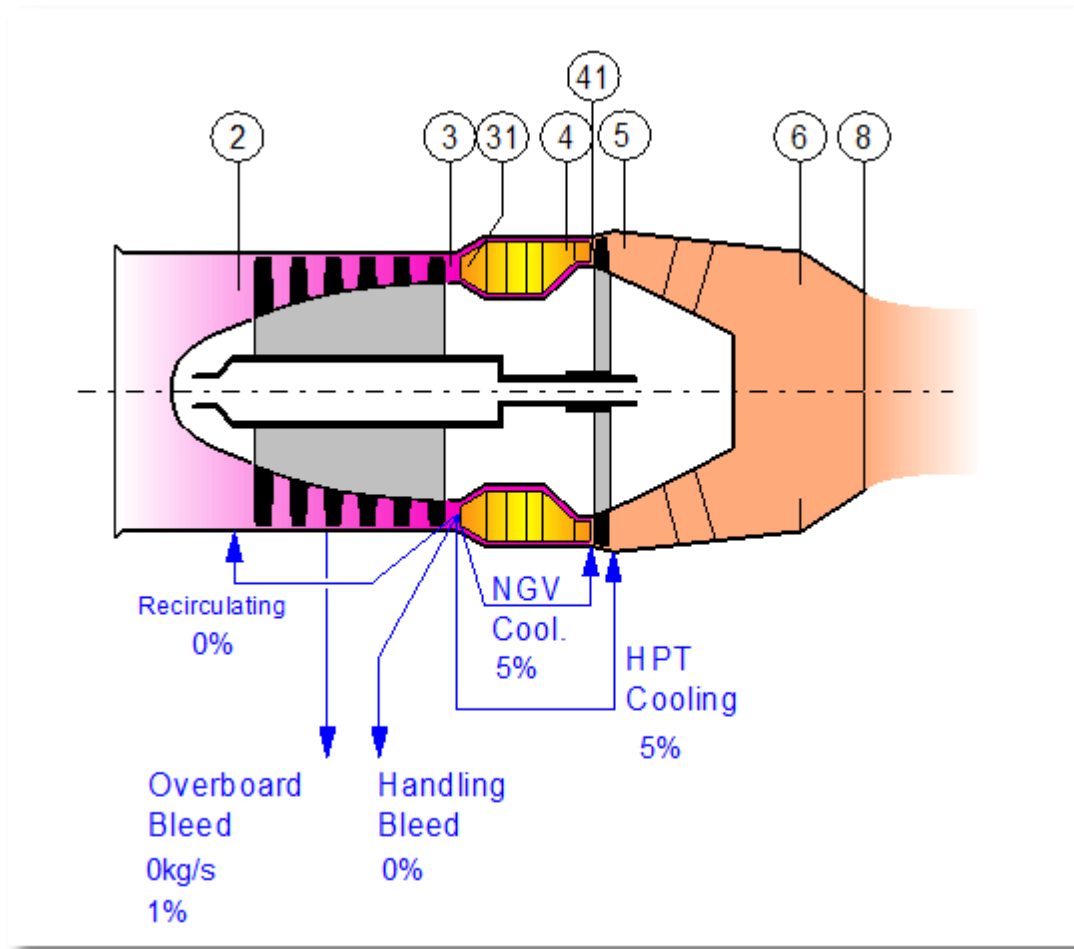
Before running the file TurbojetDeckDemo.xls make sure that the correct path to the DLL is introduced in the declaration section of the VBA program. After starting Excel (macros activated) use Alt+F11 for opening the VBA editor and replace the DLL path information - which is valid only on the computer of the DLL author - with the path to the place where you have stored the DLL on your computer.

The calculation options in the Excel file are essentially the same as those in the Test Main program.

5 Nomenclature and Units

5.1 Station Designation

The station definition used in the program follows the international standard for performance computer programs. This standard has been published by the Society of Automotive Engineers SAE as ARP 755C.



The thermodynamic station names are defined as follows:

- 0 ambient
- 1 aircraft-engine interface
- 2 first compressor inlet
- 3 last compressor exit, cold side heat exchanger inlet
- 31 burner inlet
- 4 burner exit
- 41 first turbine stator exit = rotor inlet
- 5 turbine exit after addition of cooling air
- 6 jet pipe inlet, reheat entry
- 8 nozzle throat
- 9 nozzle exit (convergent-divergent nozzle only)

5.2 Units

The functions and procedures in the DLL employ [SI units](#).

| | |
|-----------------------|----------------|
| Altitude | m |
| Temperature | K |
| Pressure | kPa |
| Mass Flow | kg/s |
| Shaft Power | kW |
| Thrust | kN |
| SFC | g/(kN s) |
| Velocity, Spec.Thrust | m/s |
| Area | m ² |

6 Engine Program Performance Options

6.1 Engine Model File

The Engine Model File that is read during the initialization of the DLL must have been created with GasTurb 12. The following restrictions apply:

- SI units must be selected when writing the Engine Model File
- Both [rel N for PLA = 0%](#) and [rel N for PLA = 100%](#) must be set to reasonable values. The input for these two quantities is found on the Transient Input Page in the Off-Design Input window of GasTurb 12.
- Steady state limiters must be switched on, both min and max limiters must be defined.
- If transient limiters are not constant, then the respective iteration must be defined. The input of this iteration and the required composed values is selectable from the transient input window.
- An intake map must be read from file before writing the Engine Model File from within GasTurb 12. This intake map, however, needs not necessarily be employed in the calculation.
- SMode must be set to 1.

6.1.1 Steady State Limiters

Limiters can be single valued or follow a schedule. How to employ control schedules is described in the GasTurb 12 help system and the manual.

Besides the pre-defined limiters up to three composed values can be employed as additional limiters. Note that drop-down lists with composed values (on the bottom left side of the limiter input page in GasTurb 12) will appear only if at least one composed value is defined.

In the Engine Model File delivered as an example for the Turbojet Deck application the idle spool speed is a function of altitude:

$$N_{idle} = 60 + 0.002 * \text{Altitude}$$

The first composed value for steady state off-design operation is defined as

$$cp_val1 = XN_HPC * 100 / (60 + 0.002 * \text{alt})$$

This composed value is employed as a [Min Limiter](#) with the min value of [1.0](#)

6.1.2 Transient Limiters

During transient operation with the GasTurb 12 control system active all the steady state limiters are activated as set in the Engine Model File. Additionally the transient limiters like dN/dt_{min} and dN/dt_{max} , for example, are active.

If you want dN/dt_{max} make a function of spool speed, for example, then you must employ an additional iteration combined with a composed value. The definitions of the composed value for transient operation and the iteration can be accessed from the menu in the transient window of GasTurb 12.

In the Engine Model File delivered as an example for the Turbojet Deck application dN/dt_{max} is a function of spool speed. The first composed value for transient operation is defined as

$$cp_val1 = 0.2 - 0.15 * XN_HPC$$

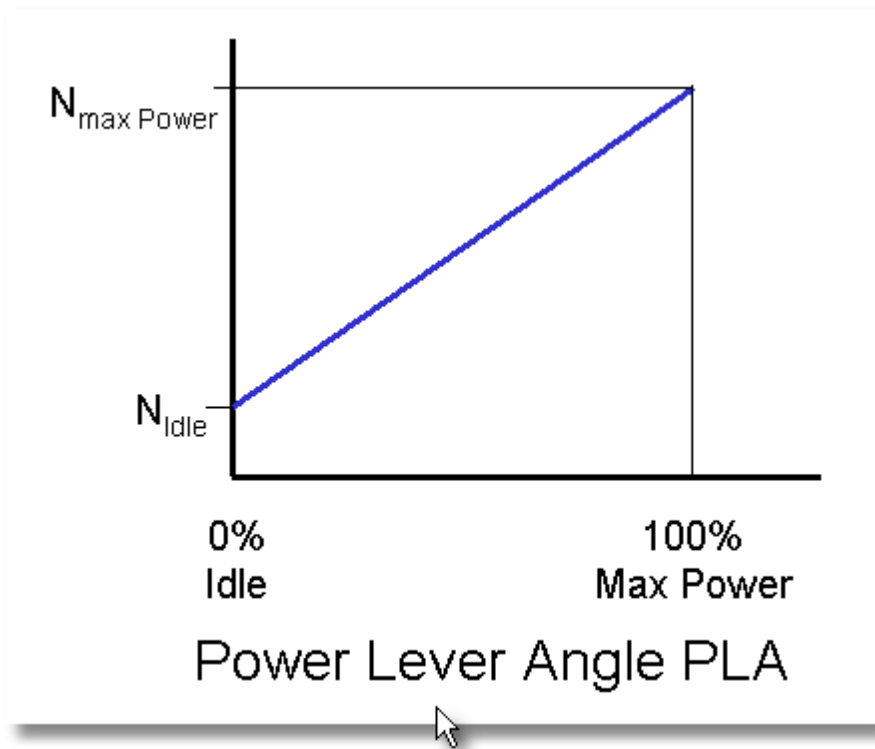
The input value for dN/dt_{max} is iterated in such a way that it equals cp_val1 .

For running the simulation with modified limiter settings a new Engine Model File must be created.

6.2 Power Lever Angle

The power level selection is controlled by the input value for the Power Code ZPC. If ZPC is 0, then the Power Lever Angle input ZPLA will be used. However, any valid Rating Code ZRC will overwrite the ZPLA input.

In the Turbojet Deck the power lever angle is linearly connected with the spool speed. N_{max} Power is equal to [rel N for PLA = 100%](#) as defined on the Transient Input Page of GasTurb 12 and N_{idle} corresponds to [rel N for PLA = 0%](#).



6.3 Power Code

The following Power Codes are defined:

| | |
|----------|---|
| PC = 50 | Maximum |
| PC = 20 | Idle |
| PC = 0 | Power Lever Angle input is active, however, any valid Rating Code input ZRC overrules the Power Lever Angle input |
| PC = -1 | run to net thrust ZFN (control system active) |
| PC = -2 | run to fuel flow ZWF (control system active, except fuel flow schedule) |
| PC = -3 | run to spool speed ZXNRPM (control system active) |
| PC = -11 | run to net thrust ZFN (control system inactive) |
| PC = -12 | run to net fuel flow ZWF (control system inactive) |
| PC = -13 | run to spool speed ZXNRPM (control system inactive) |

6.4 Rating Code

There are two valid Rating Codes defined:

1. Rating code ZRC = 50 selects maximum power
2. ZRC = 20 selects idle.

7 Input/Output

The input and output data are arranged in four groups that correspond with the COMMON blocks FIXIN, VARIN, FIXOUT and VAROUT as defined in AS681.

7.1 FIXIN

FIXIN properties are as defined in AS681. Some of them are not applicable, some of them are not used in the Turbojet Deck. Note that all data that are transferred to the functions and procedures in the DLL are of the type [double](#).

FIXIN:

| | | |
|--------|--------|----------|
| NIN | | not used |
| NOUT | | not used |
| IND | | 1,001 |
| TITLE | | Turbojet |
| CASE | | 1 |
| ZALT | [m] | 0 |
| ZDTAMB | [K] | 10 |
| ZDT1A | | not used |
| ZERM1A | | 0,99 |
| ZPWXH | [kW] | 0 |
| ZPAMB | [kPa] | 0 |
| ZPC | | 0 |
| ZPLA | | 90 |
| ZP1A | | 0 |
| ZRC | | 0 |
| SERAM | | 2 |
| SIM | | 1 |
| ZTAMB | | not used |
| ZT1A | [K] | 0 |
| ZWB3 | [kg/s] | 0 |
| ZWB3Q | | 0,01 |

| | | |
|--------|-----|----------|
| ZXM | | 0 |
| ZERAM1 | | n/a |
| ZERM11 | | n/a |
| -- | | not used |
| -- | | not used |
| -- | | not used |
| -- | | not used |
| SDIST | | not used |
| FYPH | | not used |
| FYSH | | not used |
| ZPWSD | | n/a |
| ZTIME | [s] | 0 |
| TIMEF1 | | not used |
| TIMEF2 | | not used |
| TIMEO | | not used |
| ZTIMET | | not used |
| ZXJPTL | | n/a |
| ZXNSD | | n/a |
| ZTRQSD | | n/a |
| SWIND | | not used |

There are two inlet modes selectable with the switch SIM:

| | | |
|------------|---|-------------------|
| SIM | 1 | ZALT, ZDTAMB, ZXM |
| | 2 | ZT1A, ZP1A, ZPAMB |

There are three options offered for the ram pressure recovery selection switch SERAM:

| | | |
|--------------|---|---|
| SERAM | 1 | subsonic: ZERAM (as SERAM=2) supersonic: $ZERAM * \{1 - 0.075 * (XM - 1)^{1.35}\}$ |
| | 2 | ZERAM |
| | 3 | ram recovery from the intake map |

7.1.1 FIXIN Parameter Definition

The SAE Aerospace Standard AS681G provides a method for the presentation of results from computer programs using FORTRAN 77.

The fixed sequence list of the parameters in the fixed input labeled common (FIXN), and the identity of these parameters (with typical nomenclature consistent with ARP755) are as follows:

| | | |
|----|------------|--|
| 1 | NIN | Input file number (INTEGER) |
| 2 | NOUT | Output file number (INTEGER) |
| 3 | IND | Engine program indicator (INTEGER) |
| 4 | TITLE (18) | User title: - dimension 18 (HOLLERITH) |
| 5 | CASE | Numerical case identification |
| 6 | ALT | Geopotential pressure altitude |
| 7 | ZDTAMB | Ambient temperature minus standard atmospheric temperature |
| 8 | ZDT1A | Temperature to be added to T1A |
| 9 | ZERM1A | Ram pressure recovery at station 1A |
| 10 | ZPWXH | Customer high pressure rotor power extraction |
| 11 | ZPAMB | Ambient pressure |
| 12 | ZPC | Power code |
| 13 | ZPLA | Power lever angle |
| 14 | ZP1A | Engine inlet total pressure at station 1A |
| 15 | ZRC | Rating code |
| 16 | SERAM | Ram pressure recovery selection |

Average Options

SERAM = 1, Selects specified ram pressure recovery

SERAM = 2, Selects input value of ram pressure recovery

SERAM = 3, Selects ram pressure recovery from user supplied subroutine (ERAMX)

| | | |
|----|--------|--|
| | | Differentiated Options |
| | | SERAM = 4, Selects input values of primary and secondary ram pressure recovery |
| | | SERAM = 5, Selects input value of primary stream ram pressure recovery and calls user supplied subroutine (ERAMX) for secondary stream ram pressure recovery |
| | | SERAM = 6, Selects primary and secondary stream ram pressure recoveries from user supplied subroutine (ERAMX) |
| 17 | SIM | Inlet mode selection |
| | | SIM = 1, Selects altitude and Mach number |
| | | SIM = 2, Selects pressure and temperatures |
| | | SIM = Other than 1 or 2 coordinated between user and supplier |
| 18 | ZTAMB | Ambient temperature |
| 19 | ZT1A | Engine inlet total temperature at station 1A |
| 20 | ZWB3 | High pressure compressor discharge bleed flow rate |
| 21 | ZWB3Q | High pressure compressor bleed flow ratio (discharge over component inlet) |
| 22 | ZXM | Free stream Mach number |
| 23 | ZERAM1 | Primary stream ram pressure recovery |
| 24 | ZERM11 | Secondary stream ram pressure recovery |
| 25 | -- | Reserved for historical consistency |
| 26 | -- | Reserved for historical consistency |
| 27 | -- | Reserved for historical consistency |
| 28 | -- | Reserved for historical consistency |
| 29 | SDIST | Inlet pressure and temperature distortion selection |
| 30 | FYPH | Primary maximum response frequency |
| 31 | FYSH | Secondary maximum response frequency |
| 32 | ZPWSD | Specified shaft power |
| 33 | ZTIME | Time from start of transient case |
| 34 | TIMEF1 | Time at which frequency is changed to FYSH |
| 35 | ZIMEF2 | Time at which frequency is changed to FYPH |
| 36 | TIMEO | Output time interval |
| 37 | ZTIMET | Termination time of transient case |
| 38 | ZXJPTL | Polar moment of inertia of power turbine load |
| 39 | ZXNSD | Specified shaft rotational speed |

| | | |
|----|--------|------------------------|
| 40 | ZTRQSD | Specified shaft torque |
| 41 | SWIND | Windmilling selection |

7.2 VARIN

| | | |
|---------------|---|--|
| SEST | 0 | begin the iteration with the values from previous point |
| | 1 | begin the iteration with ZBTAC, ZXNH, ZBTAT, ZDTRC |
| ZBTAC | | beta value in the compressor map |
| ZRXNH | | relative spool speed |
| ZBTAT | | beta value in the turbine map |
| ZDTRC | | temperature increase due to recirculating bleed air |
| ZFN | | specified net thrust |
| ZWF | | specified fuel flow |
| ZXNRPM | | specified spool speed in RPM |
| STRANS | 1 | Transient with ZPLA = f(ZTIME) input, the GasTurb control system is active |
| | 2 | Transient with ZWF = f(ZTIME) input, the GasTurb control system is inactive |
| | 3 | Transient with ZXNRPM = f(ZTIME) input, the GasTurb control system is inactive |
| ZCTRCP | | proportional constant of the GasTurb PID controller |
| ZCTRCD | | differential constant of the GasTurb PID controller |
| ZCTRCI | | integral constant of the GasTurb PID controller |

7.3 FIXOUT

FIXOUT properties are as defined in AS681. Some of them are not applicable, some of them are not used in the Turbojet Deck. Note that all data that are transferred from the functions and procedures in the DLL are of the type [double](#).

FIXOUT:

| | | |
|--------|-------------------|-----------|
| CLASS | | not used |
| IDENT | | not used |
| NSI | | 0 |
| AE8 | [m ²] | 0,0759551 |
| AE18 | | n/a |
| ANGBT | | not used |
| FRAM | [kN] | 0 |
| FG | [kN] | 25,4526 |
| FGI | [kN] | not used |
| FG19 | [kN] | n/a |
| FGI19 | [kN] | n/a |
| FHV | [MJ/kg] | 43,124 |
| FN | [kN] | 25,4526 |
| PB3 | [kPa] | 1203,74 |
| P7 | [kPa] | 343,983 |
| P17 | | n/a |
| SFC | [g/(kN*s)] | 24,9687 |
| -- | | not used |
| TB3 | | 651,127 |
| TC | | not used |
| T7 | [K] | 1082,75 |
| T17 | [K] | n/a |
| WFE | [kg/s] | 0,635519 |
| WFT | [kg/s] | 0,635519 |
| W1A | [kg/s] | 31,1442 |
| W7 | [kg/s] | 31,4683 |
| W17 | | n/a |
| W2 | [kg/s] | 31,1442 |
| XNH | [RPM] | 14283,9 |
| XNI | | n/a |
| XNL | | n/a |
| XNSD | | n/a |
| ALT | [m] | 0 |
| ERAM1A | | not used |

| | | |
|--------|--------|----------|
| ERAM1A | | not used |
| PAMB | [kPa] | 101,325 |
| PLA | | 90 |
| P1A | [kPa] | 100,312 |
| TAMB | [K] | 298,15 |
| T1A | [K] | 298,15 |
| XM | | 0 |
| SML | | n/a |
| SMI | | n/a |
| SMH | | 32,8606 |
| -- | | not used |
| -- | | not used |
| PWSD | | n/a |
| TIME | | 0 |
| TRQSD | | n/a |
| ERAM1 | | 0,99 |
| ERAM11 | | n/a |
| -- | | not used |
| -- | | not used |
| -- | | not used |
| -- | | not used |
| DTAMB | [K] | 0 |
| DT1A | | not used |
| PC | | 0 |
| RC | | 0 |
| WB3 | [kg/s] | 0,311442 |
| WB3Q | | 0,01 |
| PWXH | [kW] | 0 |

7.3.1 FIXOUT Parameter Definition

The SAE Aerospace Standard AS681G provides a method for the presentation of results from computer programs using FORTRAN 77.

The fixed sequence list of the parameters in the fixed output labeled common (FIXOUT), and the identity of these parameters (with typical nomenclature consistent with ARP755) are as follows:

- 1 CLASS (6) Engine program security classification - Dimension 6 (HOLLERITH)
- 2 IDENT (36) Engine program titles - Dimension 36 (HOLLERITH)

| | | |
|----|----------|--|
| 3 | NSI (10) | Numerical Status Indicator - Dimension 10 (INTEGER) |
| 4 | AE8 | Primary exhaust nozzle throat effective area |
| 5 | AE18 | Bypass exhaust nozzle throat effective area |
| 6 | ANGBT | Boat-tail angle |
| 7 | FRAM | Ram drag |
| 8 | FG | Gross thrust |
| 9 | FGI | Ideal gross thrust |
| 10 | FG19 | Bypass stream gross thrust |
| 11 | FGI19 | Bypass stream ideal gross thrust |
| 12 | FHV | Fuel lower heating value |
| 13 | FN | Net thrust |
| 14 | PB3 | High pressure compressor discharge bleed flow total pressure |
| 15 | P7 | Primary exhaust flow total pressure |
| 16 | P17 | Bypass exhaust flow total pressure |
| 17 | SFC | Specific fuel consumption |
| 18 | -- | Reserved for historical consistency |
| 19 | TB3 | High pressure compressor discharge bleed flow total temperature |
| 20 | TC | Control temperature (cockpit display) |
| 21 | T7 | Primary exhaust flow total temperature |
| 22 | T17 | Bypass exhaust flow total temperature |
| 23 | WFE | Engine fuel flow rate |
| 24 | WFT | Total fuel flow rate |
| 25 | W1A | Engine inlet flow rate at station 1A |
| 26 | W7 | Primary exhaust flow rate |
| 27 | W17 | Bypass exhaust flow rate |
| 28 | W2_ | High pressure compressor inlet flow rate (The full number representing the relevant station designation, e.g., W21, W215, W2A, will be defined by the program supplier.) |
| 29 | XNH | High pressure rotor rotational speed |
| 30 | XNI | Intermediate pressure rotor rotational speed |
| 31 | XNL | Low pressure rotor rotational speed |

| | | |
|----|--------|--|
| 32 | XNSD | Delivered shaft rotational speed |
| 33 | ALT | Geopotential pressure altitude |
| 34 | ERAM1A | Ram pressure recovery at station 1A |
| 35 | PAMB | Ambient pressure |
| 36 | PLA | Power lever angle |
| 37 | P1A | Engine inlet total pressure at station 1A |
| 38 | TAMB | Ambient temperature |
| 39 | T1A | Engine inlet total temperature at station 1A |
| 40 | XM | Free stream Mach number |
| 41 | SML | Low Pressure Compressor Surge Margin |
| 42 | SMI | Intermediate Pressure Compressor Surge Margin |
| 43 | SMH | High Pressure Compressor Surge Margin |
| 44 | -- | Reserved for historical consistency |
| 45 | -- | Reserved for historical consistency |
| 46 | PWSD | Delivered shaft power |
| 47 | TIME | Output Time, from start of transient case |
| 48 | TRQSD | Delivered shaft torque |
| 49 | ERAM1 | Primary stream ram pressure recover |
| 50 | ERAM11 | Secondary stream ram pressure recover |
| 51 | -- | Reserved for historical consistency |
| 52 | -- | Reserved for historical consistency |
| 53 | -- | Reserved for historical consistency |
| 54 | -- | Reserved for historical consistency |
| 55 | DTAMB | Ambient temperature minus standard atmosphere temperature |
| 56 | DT1A | Temperature added to T1A |
| 57 | PC | Power code |
| 58 | RC | Rating code |
| 59 | WB3 | High pressure compressor discharge total bleed flow rate (Resultant from combined inputs no 20 and 21 of FIXIN) |
| 60 | WB3Q | High pressure compressor total bleed flow ratio (discharge over component inlet) |

(Resultant from combined inputs no 20 and 21 of FIXIN)

61 PWXH Customer high pressure rotor power extraction

7.4 VAROUT

| | |
|-------|---|
| humid | relative humidity [%] |
| T2 | compressor inlet temperature |
| T3 | compressor exit temperature |
| T4 | burner exit temperature |
| T41 | turbine stator exit temperature |
| T5 | turbine exit temperature |
| P3 | compressor exit) pressure |
| PS3 | compressor exit static pressure |
| P5 | turbine exit pressure |
| NHDOT | spool speed change, % per second |
| FAR4 | burner fuel-air-ratio |
| LIMCD | limiter code |
| BTAC | beta value in the compressor map |
| RXNH | relative spool speed |
| BTAT | beta value in the turbine map |
| DTRC | temperature increase due to recirculating bleed air |

8 Program Messages

8.1 Numerical Status Indicator NSI

The following Numerical Status Indicator values are defined:

| | |
|------|----------------------------------|
| 0 | Valid result |
| 600 | A component map was extrapolated |
| 1600 | Surge margin < 0 |
| 9100 | Calculation did not converge |

| | |
|------|---|
| 9199 | Severe computing problem |
| 9201 | SIM must be 1 or 2 |
| 9202 | ZP1A, ZT1A or ZPAMB=0 while SIM=2 |
| 9203 | SIM=2 can not be combined with SERAM=3 |
| 9204 | SERAM must be 1, 2 or 3 |
| 9210 | ZRC not defined |
| 9290 | Power Lever Angle PLA definition error |
| 9291 | Engine model error: SMode must be equal to 1 |
| 9292 | STRANS must be 1, 2 or 3 during transient operation |
| 9293 | TIME >= ZTIME is not permitted |

8.2 Steady State Limiter Codes

During steady state simulations the following limiter codes are used:

| | | |
|----|-------------|--|
| -5 | cp_val_min3 | value of the third cp_val min limiter |
| -4 | cp_val_min2 | value of the second cp_val min limiter |
| -3 | cp_val_min1 | value of the first cp_val min limiter |
| -2 | WF_min | min fuel flow |
| -1 | NH_min | min gas generator spool speed |
| 0 | | operation within limits or no limiters activated |
| 1 | NL_max | max low-pressure spool speed |
| 2 | NLR_max | max corrected low-pressure spool speed |
| 3 | NH_max | max high-pressure spool speed |
| 4 | NHR_max | max corrected high-pressure spool speed |
| 5 | T3_max | max burner inlet temperature |
| 6 | P3_max | max burner inlet pressure |
| 7 | T41_max | max stator outlet temperature (SOT) |
| 8 | T45_max | max low-pressure turbine inlet temperature |
| 9 | T5_max | max turbine exit temperature |
| 10 | TRQ_max | max torque |
| 11 | cp_val_max1 | value of the first cp_val max limiter |

| | | |
|----|-------------|--|
| 12 | cp_val_max2 | value of the second cp_val max limiter |
| 13 | cp_val_max3 | value of the third cp_val max limiter |

8.3 Transient Limiter Codes

During transient simulations the limiter code LIMCD in VAROUT can have the following values:

| | | |
|----|-------------|-------------------------------------|
| 0 | | control system switched off |
| 1 | Control | operation within limits |
| 2 | N | max spool speed |
| 3 | N,corr | max corrected spool speed |
| 4 | T3 | max burner inlet temperature |
| 5 | P3 | max burner inlet pressure |
| 6 | T41 | max stator outlet temperature (SOT) |
| 7 | T5 | max turbine exit temperature |
| 8 | cp_val_max1 | max composed value 1 |
| 9 | cp_val_max2 | max composed value 2 |
| 10 | cp_val_max3 | max composed value 3 |
| 11 | N_dot_max | max dN/dt (acceleration) |
| 12 | far max | max fuel-air-ratio (acceleration) |
| 13 | WF/P3 max | max WF/P3 (acceleration) |
| 14 | WF max | max fuel flow |
| 15 | N_dot_min | min dN/dt (deceleration) |
| 16 | far_min | min fuel-air-ratio (deceleration) |
| 17 | WF/P3 min | min WF/P3 (deceleration) |
| 18 | Nmin | min spool speed |
| 19 | WF min | min fuel flow |
| 20 | cp_val_min1 | min composed value 1 |
| 21 | cp_val_min2 | min composed value 2 |
| 22 | cp_val_min3 | min composed value 3 |

8.4 About Convergence Problems

Any off-design gas turbine performance simulation program requires iteration. That means that the values of some variables must be estimated at the beginning of the calculation. Corresponding with the number of iteration variables there is an equal number of conditions within the mathematical model of the gas turbine. While the iteration variables do not have their correct value, then some or all of the conditions are not fulfilled. A sophisticated algorithm varies the variables iteratively in such a way that all the conditions are fulfilled when the calculation is finished.

Sometimes the iteration fails to converge which is indicated by NSI=9100. Non-convergence can have many reasons: sometimes one or the other of the normal input properties are unreasonable, sometimes the start values of the iteration variables are far away from those of the solution, sometimes the solution requires one or more components operating far outside of their respective component maps.

In this computer deck the output values of the iteration variables are BTAC, RXNH, BTAT and DTRC in the VAROUT group. While SEST is zero, these values are employed as estimates for the next point to be calculated. If a point has not converged, then most probably the values of BTAC, RXNH, BTAT and DTRC are unreasonable and not suited as estimate for the next case to be calculated. For recovering from this situation, SEST can be set to 1 which makes the iteration begin with the values ZBTAC, ZXNH, ZBTAT, ZDTRC from the VARIN group.

If the iteration fails to converge because the operating conditions between two steady state points are very different - an idle case followed by a max rating case, for example - then the problem can be avoided eventually by introducing a few intermediate rating steps.

Convergence problems that are not understood can be examined with GasTurb 12. In this program there are many more diagnostic options available than in this computer deck.

If none of the advice given above helps then it might be that no solution exists. This can be the case for excessive power or bleed off-take, for example.

If in transient simulations a convergence problem shows up while one of the input properties changes significantly in a very short time, then the time step might be too big. This is similar to the case when the spool speed input (while STRANS=3) implies excessive \dot{N} (dN/dt) values.

If during a transient simulation the iteration converges after having failed at one or a few prior time steps, then the convergence problem can mostly be ignored.

9 Test Cases

9.1 Cycle Reference Point

During initialization of the DLL the GasTurb cycle reference point is written to the input (i.e. FIXIN and VARIN) and the output (FIXOUT and VAROUT) groups.

9.2 Steady State Off-Design

The performance point to be calculated is defined by the data given in FIXIN and VARIN. For a steady state point ZTIME must be set to zero.

9.3 Transient

A transient simulation is performed if the FIXIN property ZTIME has a positive value greater than the FIXOUT property TIME from the previously calculated point.

Three examples are selectable in the test main program respectively in the Excel sheet:

- a 10% step increase in fuel flow which demonstrates the fuel flow input option (STRANS=2)
- a PLA maneuver with a slam deceleration followed by a slam acceleration
- a spool speed input as a function of time

10 Identification and Revision Procedure

The version of the DLL can be read by calling the function GetDLLVersion.

The responsibility for the data is with the provider of the Engine Model File.

11 References

[1] SAE
AEROSPACE STANDARD AS681 Rev. G
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[2] J. Kurzke
GasTurb 12 User Manual
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